

## Lecture 22. (Sketch.)

- ▶ Homework 2 due Wednesday.
- ▶ Today and on Wednesday, we'll discuss VC bound for neural networks. These bounds have a bad reputation as “loose”, “impractical”, vacuous. so why are we studying them?
  - ▶ They reveal and are sensitive to some interesting structure in networks (the total possible number of activation patterns).
  - ▶ Before we “worst-case-ify” the bounds and have  $\ln \text{Sh}(\mathcal{F}|_S)$ , it seems they could somehow be made average-case-y and tighter, though I don't know how yet. . .

## 2. VC dimension of linear predictors.

**Theorem.** Define  $\mathcal{F} := \{x \mapsto \text{sgn}(\langle a, x \rangle - b) : a \in \mathbb{R}^d, b \in \mathbb{R}\}$  (“linear classifiers”/“affine classifier”/ “linear threshold function (LTF)”). Then  $\text{VC}(\mathcal{F}) = d + 1$ .

### Remarks.

- ▶ By Sauer-Shelah,  $\text{Sh}(\mathcal{F}; n) \leq n^{d+1} + 1$ . Anthony-Bartlett chapter 3 gives an exact equality; only changes constants of  $\ln \text{VC}(\mathcal{F}; n)$ .
- ▶ Let's compare to Rademacher:

$$\begin{aligned} \text{URad}(\text{sgn}(\mathcal{F}|_S)) &\leq \sqrt{2nd \ln(n+1)}, \\ \text{URad}(\mathbb{R}^x \mapsto \langle w, x \rangle : \|w\| \leq R\}_{|S}) &\leq R \|X_S\|_F, \end{aligned}$$

where  $\|X_S\|_F^2 = \sum_{x \in S} \|x\|_2^2 \leq n \cdot d \cdot \max_{i,j} x_{i,j}$ . One is scale-sensitive (and suggests regularization schemes), other is scale-insensitive.

## 1. VC Theory recap.

A few definitions:

$$\begin{aligned} \text{sgn}(U) &:= \{(\text{sgn}(u_1), \dots, \text{sgn}(u_n)) : u \in V\}, \\ \text{Sh}(\mathcal{F}|_S) &:= |\text{sgn}(\mathcal{F}|_S)|, \\ \text{Sh}(\mathcal{F}; n) &:= \sup_{|S| \leq n} |\text{sgn}(\mathcal{F}|_S)|, \\ \text{VC}(\mathcal{F}) &:= \sup\{i \in \mathbb{Z}_{\geq 0} : \text{Sh}(\mathcal{F}; i) = 2^i\}. \end{aligned}$$

**Theorem** (“VC Theorem”). With probability at least  $1 - \delta$ , every  $f \in \mathcal{F}$  satisfies

$$\mathcal{R}_z(\text{sgn}(f)) \leq \widehat{\mathcal{R}}_z(\text{sgn}(f)) + \frac{2}{n} \text{URad}(\text{sgn}(\mathcal{F}|_S)) + 3\sqrt{\frac{\ln(2/\delta)}{2n}},$$

and

$$\begin{aligned} \text{URad}(\text{sgn}(\mathcal{F}|_S)) &\leq \sqrt{2n \ln \text{Sh}(\mathcal{F}|_S)}, \\ \ln \text{Sh}(\mathcal{F}|_S) &\leq \ln \text{Sh}(\mathcal{F}; n) \leq \text{VC}(\mathcal{F}) \ln(n+1). \end{aligned}$$

**Proof** of lower bound  $\text{VC}(\mathcal{F}) \geq d + 1$ .

- ▶ Suffices to show  $\exists S := \{x_1, \dots, x_{d+1}\}$  with  $\text{Sh}(\mathcal{F}|_S) = 2^{d+1}$ .
- ▶ Choose  $S := \{\mathbf{e}_1, \dots, \mathbf{e}_d, (0, \dots, 0)\}$ .

Given any  $P \subseteq S$ , define  $(a, b)$  as

$$a_i := 2 \cdot \mathbb{1}[\mathbf{e}_i \in P] - 1, \quad b := \frac{1}{2} - \mathbb{1}[0 \in P].$$

Then

$$\begin{aligned} \text{sgn}(\langle a, \mathbf{e}_i \rangle - b) &= \text{sgn}(2\mathbb{1}[\mathbf{e}_i \in P] - 1 - b) = 2\mathbb{1}[\mathbf{e}_i \in P] - 1, \\ \text{sgn}(\langle a, 0 \rangle - b) &= \text{sgn}(2\mathbb{1}[0 \in P] - 1/2) = 2\mathbb{1}[0 \in P] - 1, \end{aligned}$$

meaning this affine classifier labels  $S$  according to  $P$ , which was an arbitrary subset.

**Proof** (of upper bound  $VC(\mathcal{F}) < d + 2$ ).

- ▶ Consider any  $S \subseteq \mathbb{R}^d$  with  $|S| = d + 2$ .
- ▶ By *Radon's Lemma* (proved on next page), there exists a partition of  $S$  into nonempty  $(P, N)$  with  $\text{conv}(P) \cap \text{conv}(N)$ .
- ▶ Label  $P$  as positive and  $N$  as negative. Given any affine classifier, it can not be correct on all of  $S$  (and thus  $VC(\mathcal{F}) < d + 2$ ): either it is incorrect on some of  $P$ , or else it is correct on  $P$ , and thus has a piece of  $\text{conv}(N)$  and thus  $x \in N$  labeled positive.

**Theorem** (Radon's Lemma). Given  $S \subseteq \mathbb{R}^d$  with  $|S| = d + 2$ , there exists a partition of  $S$  into nonempty  $(P, N)$  with  $\text{conv}(P) \cap \text{conv}(N) \neq \emptyset$ .

**Proof.** Let  $S = \{x_1, \dots, x_{d+2}\}$  be given, and define  $\{u_1, \dots, u_{d+1}\}$  as  $u_i := x_i - x_{d+2}$ , which must be linearly dependent:

- ▶ Exist scalars  $(\alpha_1, \dots, \alpha_{d+1})$  and a  $j$  with  $\alpha_j := -1$  so that

$$\sum_i \alpha_i u_i = -u_j + \sum_{i \neq j} \alpha_i u_i = 0;$$

- ▶ thus  $x_j - x_{d+2} = \sum_{\substack{i \neq j \\ i < d+2}} \alpha_i (x_i - x_{d+2})$  and  $0 = \sum_{i < d+2} \alpha_i x_i - x_{d+2} \sum_{i < d+2} \alpha_i =: \sum_j \beta_j x_j$ , where  $\sum_j \beta_j = 0$  and not all  $\beta_j$  are zero.

**Proof** (continued).

Set  $P := \{i : \beta_i > 0\}$ ,  $N := \{i : \beta_i \leq 0\}$ ; where neither set is empty.

Set  $\beta := \sum_{i \in P} \beta_i - \sum_{i \in N} \beta_i > 0$ .

Since  $0 = \sum_i \beta_i x_i = \sum_{i \in P} \beta_i x_i + \sum_{i \in N} \beta_i x_i$ , then

$$\frac{0}{\beta} = \sum_{i \in P} \frac{\beta_i}{\beta} x_i + \sum_{i \in N} \frac{\beta_i}{\beta} x_i$$

and the point  $z := \sum_{i \in P} \beta_i x_i / \beta = \sum_{i \in N} \beta_i x_i / (-\beta)$  satisfies  $z \in \text{conv}(P) \cap \text{conv}(N)$ .

**Remarks.**

- ▶ Generalizes Minsky-Papert "xor" construction from lecture 2.
- ▶ Indeed, the first appearance I know of shattering/VC was in approximation theory, the papers of Warren and Shapiro, and perhaps it is somewhere in Kolmogorov's old papers.

### 3. VC dimension of LTF networks.

Consider iterating the previous construction, giving an “LTF network”: a neural network with activation  $z \mapsto \mathbb{1}[z \geq 0]$ .

We’ll analyze this by studying output of all nodes. To analyze this, we’ll study not just the outputs, but the behavior of all nodes.

#### Definition.

- ▶ Given a sample  $S$  of size  $n$  and an LTF network with  $m$  nodes (in any topologically sorted order), define activation matrix  $A := \text{Act}(S; W := (a_1, \dots, a_m))$  where  $A_{ij}$  is the output of node  $j$  on input  $i$ , with fixed network weights  $W$ .
- ▶ Let  $\text{Act}(S; \mathcal{F})$  denote the set of activation matrices with architecture fixed and weights  $W$  varying.

#### Remarks.

- ▶ Since last column is the labeling,  $|\text{Act}(S; \mathcal{F})| \geq \text{Sh}(\mathcal{F}|_S)$ .
- ▶ Act seems a nice complexity measure, but it is hard to estimate given a single run of an algorithm (say, unlike a Lipschitz constant).
- ▶ We’ll generalize Act to analyze ReLU networks.

#### Theorem.

For any LTF architecture  $\mathcal{F}$  with  $p$  parameters,

$$\text{Sh}(\mathcal{F}; n) \leq |\text{Act}(S; \mathcal{F})| \leq (n + 1)^p.$$

When  $p \geq 12$ , then  $\text{VC}(\mathcal{F}) \leq 6p \ln(p)$ .

#### Proof.

- ▶ Topologically sort nodes, let  $(p_1, \dots, p_m)$  denote numbers of respective numbers of parameters (thus  $\sum_i p_i = p$ ).
- ▶ Proof will iteratively construct sets  $(U_1, \dots, U_m)$  where  $U_i$  partitions the weight space of nodes  $j \leq i$  so that, within each partition cell, the activation matrix does not vary.
- ▶ The proof will show, by induction, that  $|U_i| \leq (n + 1)^{\sum_{j \leq i} p_j}$ . This completes the proof of the first claim, since  $\text{Sh}(\mathcal{F}|_S) \leq |\text{Act}(\mathcal{F}; S)| = |U_m|$ .
- ▶ For convenience, define  $U_0 = \{\emptyset\}$ ,  $|U_0| = 1$ ; the base case is thus  $|U_0| = 1 = (n + 1)^0$ .

#### Proof (inductive step).

Let  $j \geq 1$  be given; the proof will now construct  $U_{j+1}$  by refining the partition  $U_j$ .

- ▶ Fix any cell  $C$  of  $U_j$ ; as these weights vary, the activation is fixed, thus the input to node  $j + 1$  is fixed for each  $x \in S$ .
- ▶ Therefore, on this augmented set of  $n$  inputs ( $S$  with columns of activations appended to each example), there are  $(n + 1)^{p_{j+1}}$  possible outputs via Sauer-Shelah and the VC dimension of affine classifiers with  $p_{j+1}$  inputs.
- ▶ In other words,  $C$  can be refined into  $(n + 1)^{p_{j+1}}$  sets; since  $C$  was arbitrary,

$$|U_{j+1}| = |U_j|(n + 1)^{p_{j+1}} \leq (n + 1)^{\sum_{l \leq j+1} p_l}.$$

**Proof** (VC dimension bound).

It remains to bound the VC dimension via this Shatter bound:

$$\begin{aligned} \text{VC}(\mathcal{F}) &< n \\ \iff \forall i \geq n \cdot \text{Sh}(\mathcal{F}; i) &< 2^i \\ \iff \forall i \geq n \cdot (i+1)^p &< 2^i \\ \iff \forall i \geq n \cdot p \ln(i+1) &< i \ln 2 \\ \iff \forall i \geq n \cdot p < \frac{i \ln(2)}{\ln(i+1)} \\ \iff p < \frac{n \ln(2)}{\ln(n+1)} \end{aligned}$$

If  $n = 6p \ln(p)$ ,

$$\begin{aligned} \frac{n \ln(2)}{\ln(n+1)} &\geq \frac{n \ln(2)}{\ln(2n)} = \frac{6p \ln(p) \ln(2)}{\ln 2 + \ln p + \ln \ln p} \\ &\geq \frac{6p \ln p \ln 2}{3 \ln p} > p. \end{aligned}$$

**Remarks.**

- ▶ Had to do handle  $\forall i \geq n$  since VC dimension is defined via sup; one can define funky  $\mathcal{F}$  where Sh is not monotonic in  $n$ .
- ▶ Lower bound is  $\Omega(p \ln m)$ ; see Anthony-Bartlett chapter 6 for a proof. This lower bound however is for a specific fixed architecture!
- ▶ Other VC dimension bounds: ReLU networks have  $\tilde{O}(pL)$ , sigmoid networks have  $\tilde{O}(p^2 m^2)$ , and there exists a convex-concave activation which is close to sigmoid but has VC dimension  $\infty$ .
- ▶ Matching lower bounds exist for ReLU, not for sigmoid; but even the “matching” lower bounds are deceptive since they hold for a *fixed* architecture of a given number of parameters and layers.