

Lecture 20: Positive homogeneity & low norm solutions

Reminders:

(Clarke differential $\partial f(w) = \left\{ \lim_i \nabla f(w_i) : \begin{array}{l} w_i \rightarrow w \\ \nabla f(w_i) \text{ exists} \\ \lim_i \nabla f(w_i) \text{ exists} \end{array} \right\}$)

good: locally Lipschitz \Rightarrow nonempty everywhere

bad: technical issues (are regularity, nonuniqueness of flows) does not match pytorch

Positive homogeneity: f is L homogeneous $\forall c > 0 \quad f(cw) = c^L f(w)$.
(e.g., abstraction of L -layer ReLU network without biases)

key property
 $\forall s \in \partial f(w), \langle s, w \rangle = L f(w)$.

$$\begin{aligned} \sigma(c \cdot x) &= \max \{0, cx\} = c \sigma(x) \\ F(x; cw) &= F(x; (cW_2, cb_2, cW_1)) \\ &= cW_2 \sigma(cW_1 x) + cb_2 \\ &= c^2 W_2 \sigma(w_1 x) + \boxed{cb_2} \end{aligned}$$

not pos-hom if $b_2 \neq 0$.

Plan: ① prove & example

② "norm preservation" $\|W_i(t) - W_i(w)\|$
vs. $\|W_k(t) - W_k(w)\|$

③ low norm solutions in optimization

Positive homogeneity & gradients

$$\langle \partial f(w), w \rangle = \{ L f(w) \} \quad ???$$

ReLU network:

$$z_i := W_i x$$

$$z_{i+1} := W_{i+1} \sigma(z_i)$$

note

$$S_i := \text{diag}(\mathbb{1}_{L z_i \geq 0})$$

$$\sigma(z_i) = S_i z_i$$

$$F(x; w) = W_L \sigma(z_L) = W_L S_L z_L = W_L S_L W_{L-1} \sigma(z_{L-1})$$

$$= \dots = W_L S_L W_{L-1} S_{L-1} \dots S_1 W_1 x$$

$$\frac{d}{dw_j} F(x; w) = (W_L S_L W_{L-1} \dots W_{j+1} S_j)^T (S_{j-1} W_{j-1} \dots S_1 W_1 x)^T$$

$$\langle \partial F(x; w), w \rangle = \sum_{j=1}^L \langle \partial_{w_j} F(x; w), W_j \rangle$$

memory aid
 ① write out actual matrices
 $\frac{d}{dx} x_1 x_2 \dots x_n = x_2 \dots x_n$
 $= x_1 \dots x_{j-1} x_{j+1} \dots x_n$
 ② use transposes to match dimensions

$$\begin{aligned} \langle \partial_{w_j} F(x; w), W_j \rangle &= \langle (W_L \dots S_j)^T (S_{j-1} \dots W_1 x)^T, W_j \rangle \\ &= \text{tr} \left([(W_L \dots S_j)^T (S_{j-1} \dots W_1 x)^T]^T W_j \right) \\ &= \text{tr} \left((S_{j-1} \dots W_1 x) (W_L \dots S_j) W_j \right) \\ &= \text{tr} \left((W_L \dots S_j) W_j (S_{j-1} W_{j-1} \dots W_1 x) \right) \\ &= \text{tr} \left(F(x; w) \right) = F(x; w) \end{aligned}$$

$$\Rightarrow \langle \partial F(x; w), w \rangle = L \cdot F(x; w)$$

Reminder to future self: instead:

- ① ReLU network is piecewise affine in the input x , piecewise polynomial in the parameters
- ② locally Lipschitz \Rightarrow nondifferentiability has Lebesgue measure zero
- ③ (i) calculate gradient interior of each piece
 (ii) limits towards boundaries.

Theorem (Euler's homogeneous function theorem)

If f is locally Lipschitz $\Rightarrow \langle \partial f(w), w \rangle = \{ L f(w) \}$

Proof. 2-phase proof: ① check when differentiable ② use limits & defn Clarke

① when differentiable:

$$\begin{aligned} \langle \nabla f(w), w \rangle &= \lim_{h \rightarrow 0} \frac{f(w+h) - f(w)}{h} \\ &= \lim_{h \rightarrow 0} \frac{f((1+h)w) - f(w)}{h} \\ &= \lim_{h \rightarrow 0} \frac{(1+h)^L f(w) - f(w)}{h} \\ &= \lim_{h \rightarrow 0} \frac{(1+Lh + \frac{L(L-1)}{2}h^2 \dots) f(w) - f(w)}{h} = \lim_{h \rightarrow 0} (Lh f(w) + o(h) \dots) \\ &= L f(w) \end{aligned}$$

min $\sum_i \|w - x_i\|_1$
 Clarke book:
 has drawing of the table

② General case: $s \in \partial f(w) \Rightarrow s = \sum_i \lambda_i s_i \leftarrow \lim_{j \rightarrow \infty} \nabla f(w_{i,j})$

$$\begin{aligned} \langle s, w \rangle &= \sum_i \lambda_i \langle s_i, w \rangle = \sum_i \lambda_i \langle \lim_j \nabla f(w_{i,j}), w \rangle \\ &= \sum_i \lambda_i \lim_j \langle \nabla f(w_{i,j}), w_{i,j} \rangle = \sum_i \lambda_i \lim_j L f(w_{i,j}) \\ &= \sum_i \lambda_i L f(w) = L f(w) \end{aligned}$$

defn Clarke diff.

if $L \in \mathbb{R}_{\geq 0} \setminus \mathbb{Z} \Rightarrow$

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{f((1+h)w) - f(w)}{h} &= \lim_{h \rightarrow 0} \frac{(1+h)^L f(w) - f(w)}{h} \\ &= \lim_{h \rightarrow 0} \frac{\exp(hL) f(w) - f(w)}{h} \end{aligned}$$

into the trash.

Theorem. Consider σF with $\tilde{R}(w_t) = -\frac{1}{n} \sum_{i=1}^n l'(y_i f(x_i; w_t))$
 where $F(x; w)$ is 1-homogeneous in each layer
 $\left[\forall c \geq 0 \quad F(x; (w_1, \dots, c w_j, w_{j+1}, \dots, w_n)) = c F(x; (w_1, \dots, w_n)) \right]$
 Suppose this chain rule d.e. $\Rightarrow \partial F(x_j; w)$

Then $\forall t \geq 0 \quad \frac{1}{2} \|W_j(t)\|^2 - \frac{1}{2} \|W_j(0)\|^2 = \frac{1}{2} \|W_k(t)\|^2 - \frac{1}{2} \|W_k(0)\|^2$

Remark: for other notions of "distance to initialize" might be false.

Proof. $\frac{1}{2} \|W_j(t)\|^2 - \frac{1}{2} \|W_j(0)\|^2 = \int_0^t \frac{d}{ds} \frac{1}{2} \|W_j(s)\|^2 ds$

$$\begin{aligned} &= \int_0^t \langle \dot{W}_j(s), W_j(s) \rangle ds \\ &= \int_0^t \langle -\tilde{\partial}_{w_j} \tilde{R}(W_j(s)), W_j(s) \rangle ds \\ &= \int_0^t -\frac{1}{n} \sum l'(y_i F(x_i; w_s)) \langle \tilde{\partial}_{w_j} F(x_i; w_s), W_j(s) \rangle ds \end{aligned}$$

$$\frac{1}{2} \|W_j(t) - W_j(0)\|^2 = \int \langle \dot{W}_j(s), W_j(s) - W_j(0) \rangle ds$$

$$= \int_0^t -\frac{1}{n} \sum l'(\dots) F(x_i; w_s)$$

no dependence on layer.

other note to future self:
 prove Clarke decomposes over coordinates