

Lecture 22: L-homogeneous KKT points & project info

Last time: minimum norm predictors
 (rare because: generalize well).

local plan:

& linear pred

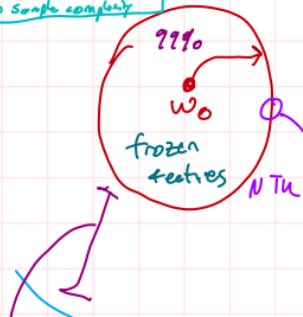
* GF on exponential or logistic loss
 $\xrightarrow{t \rightarrow \infty}$ maximum norm (classification) sdn.

$$\begin{aligned} \text{Min } & \frac{1}{2} \|w\|_2^2 \\ \text{s.t. } & y_i x_i^T w \geq 1 \quad \left| \begin{array}{l} \text{Max } \min_i y_i x_i^T w \\ \text{s.t. } \|w\|_2 \leq 1 \end{array} \right. \end{aligned}$$

* closest theorem L-homogeneous preds

global plan:

mean-field: ① tiny init
 ② small step ③ logarithmic
 ④ no sample complexity



intermediate regime:

- * still has some randomness
- * little bit of feature learning
- * matches practice

asymptotic regime

$$\|w_t\| \rightarrow \|w_0\|$$

good news:
 * includes feature learning

bad news
 * slow convergence,
 hard to prove
 / unclear
 what's true

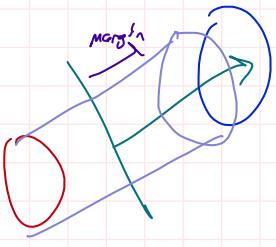
KKT points of L-homogeneous

c>0

Recall L-homogeneous predictor $F(x_i; c\omega) = c^L F(x_i; \omega)$
 (generalizes L-layer ReLU & leaky ReLU networks).

Linear case, margin

$$\max_{w \in \mathbb{R}^p} \frac{\min_i y_i F(x_i; w)}{\|w\|}$$



$$= \max_{w \in \mathbb{R}^p} \frac{\min_i \|w\|^L y_i F(x_i; w/\|w\|)}{\|w\|}$$

$$= \max_{w \in \mathbb{R}^p} \|w\|^{L-1} \min_i y_i F(x_i; w/\|w\|)$$

in linear case, = 1; in L>2 case, bogus defn.

Obvious fix:

$$\max_{w \in \mathbb{R}^p} \frac{\min_i y_i F(x_i; w)}{\|w\|^L} = \max_{\|w\| \leq 1} \min_i y_i F(x_i; w).$$

Remark: Modern networks are not L-homogeneous
 (e.g., softmax, biases).

Consider two opt problems

$$\begin{aligned} \min \frac{1}{2} \|w\|^2 \\ \text{s.t. } y_i F(x_i; w) \geq 1 + \varepsilon_i. \\ w \in \mathbb{R}^p \end{aligned}$$

[1]

$$\max_{w \in \mathbb{R}^p} \frac{-\ln \sum_i \exp(-y_i F(x_i; w))}{\|w\|^L}.$$

[2]

mean-field

Theorem: Suppose GF s.t. $L(w) = \sum_i \exp(-y_i F(x_i; w))$ and $\exists \tau$ $y(w_\tau) < 1$.

(1) $t \mapsto -\ln \frac{L(w_t)}{\|w_t\|^L}$ (i.e., objective in [2]) is nondecreasing over $[\tau, \infty)$.
 [$L_{\text{yu-Li}}$].

(2) $\frac{w_t}{\|w_t\|} \rightarrow$ KKT point of [1] ($[L_{\text{yu-Li}}], [J_i - T_i]$)
 (under σ -minimal definability).

↳ rules out oscillations; e.g., can't have $\sin(\cdot)$ activations

Proof remark: (1) note $v \mapsto \max_i v_i$ is 1-homogeneous,
 proof uses "approximate σ -minimality" of $v \mapsto -\ln \sum_i \exp(-v_i)$.

(2) KKT point proof shows "alignment": $\left\langle \frac{w_t}{\|w_t\|}, \frac{-\nabla L(w_t)}{\|\nabla L(w_t)\|} \right\rangle \rightarrow 1$.

Remark: good news: regularity outside nth.

bad news: no better than nth.

Remark: People have shown convergence global na reg'n soln,
 but it requires infinitely many assumption. [Ch. Zell-Bach]